

CS 6170: Computational Topology, Spring 2019

Lecture 09

Topological Data Analysis for Data Scientists

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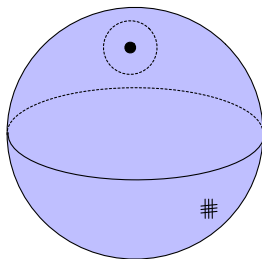
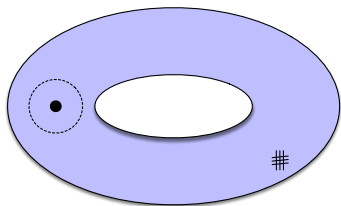
Feb 5, 2019

2-dimensional Manifold

Book Chapter A.II

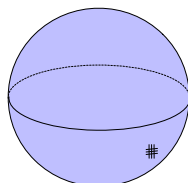
2-manifold without boundary

- A *2-manifold without boundary* is a topological space \mathbb{M} whose points all lie in open disks.
- Intuitively, this means that \mathbb{M} locally looks like a plane.
- We get a *2-manifold with boundary* by removing open disks from a 2-manifolds without boundary.

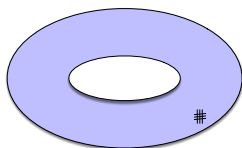


Examples of 2-manifolds

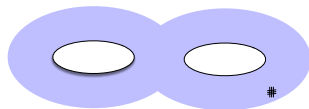
- Top: 2-manifold without boundary
- Bottom: 2-manifold with boundary
- Möbius strip: non-orientable manifold; 2 sides locally, 1 side globally.
- Möbius strip: an ant will travel all surface area
- Möbius strip: its boundary is a single circle
- Quiz: what happens if you cut Mobius strip along its center line?



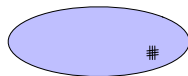
Sphere S^2



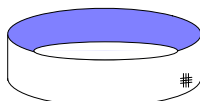
Torus T^2



Double torus $T^2 \# T^2$



Disk



Cylinder



Möbius strip

Orientability

- If all closed curves in a 2-manifold are orientation-preserving, then the 2-manifold is *orientable*.
- Creating compact 2-manifolds using *polygonal schema*.
- \mathbb{M} is compact if for every covering of \mathbb{M} by open sets, called an open cover, we can find a finite number of the sets that cover \mathbb{M} .
- A subset of Euclidean space is *compact* if it is closed and bounded (i.e., contained in a ball of finite radius).

Theorem (Classification theorem for compact 2-manifolds)

The two infinite families \mathbb{S}^2 , \mathbb{T}^2 , $\mathbb{T}^2 \# \mathbb{T}^2, \dots$, and \mathbb{P}^2 , $\mathbb{P}^2 \# \mathbb{P}^2, \dots$, exhaust the compact 2-manifolds without boundary.

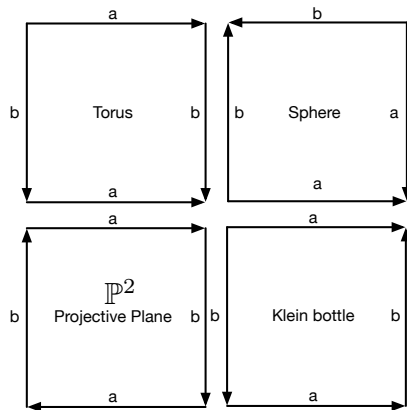
(Edelsbrunner and Harer, 2010, Page 29)

Any connected closed surface is homeomorphic to some member of one of these three families:

- The sphere
- The connected sum of g tori, for $g \geq 1$
- The connected sum of k real projective planes, for $k \geq 1$.

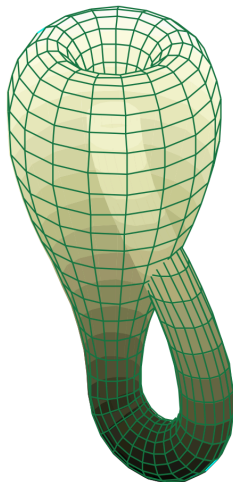
[https://en.wikipedia.org/wiki/Surface_\(topology\)#Classification_of_closed_surfaces](https://en.wikipedia.org/wiki/Surface_(topology)#Classification_of_closed_surfaces)

Polygonal schema



- Projective plane: glue a disk to a Möbius strip
- Klein bottle: glue 2 Möbius strips together

Klein bottle: non-orientable surface



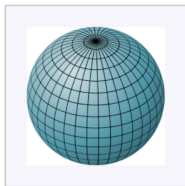
https://en.wikipedia.org/wiki/Klein_bottle

Later: show up in data analysis of natural image patches Carlsson et al. (2008).

Betti numbers β_i of 2-manifolds

	β_0	β_1	β_2
circle	1	1	0
sphere	1	0	1
torus	1	2	1
projective plane	1	0	0
Klein bottle	1	1	0
2-hole torus	1	4	1
g-hole torus	1	$2g$	1

- The *genus* of a connected, orientable surface is an integer representing the maximum number of cuttings along non-intersecting closed simple curves without disconnecting the resulting manifold.



genus 0



genus 1



genus 2



genus 3

[https://en.wikipedia.org/wiki/Genus_\(mathematics\)](https://en.wikipedia.org/wiki/Genus_(mathematics)),
also for further reading

Computing Homology

Book Chapter B.IV.

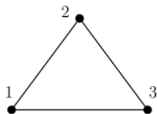
Reduction of a boundary matrix

- Let ∂_p be the p -th boundary matrix
- After reduction (row and column operation), ∂_p turns out to be a matrix N_p in Smith Normal Form
- https://en.wikipedia.org/wiki/Smith_normal_form
- $\beta_p = \text{rank } Z_p - \text{rank } B_p$

$$\text{rank } B_{p-1} \left\{ \begin{array}{cccc} & & & \overbrace{\text{rank } Z_p} \\ & & & \dots \\ & & & \dots \\ & & & \dots \\ 1 & \dots & 0 & \dots \\ & & \ddots & \\ & & & \\ 0 & & & 1 \\ \vdots & & & \\ & & & \\ & \dots & & \dots \end{array} \right\} \text{rank } C_{p-1}$$

$\underbrace{\hspace{15em}}_{\text{rank } C_p}$

Example: a triangulation of a circle



$$\partial_1 = \begin{array}{c} 12 \quad 23 \quad 31 \\ \begin{array}{c} 1 \\ 2 \\ 3 \end{array} \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \end{array}$$

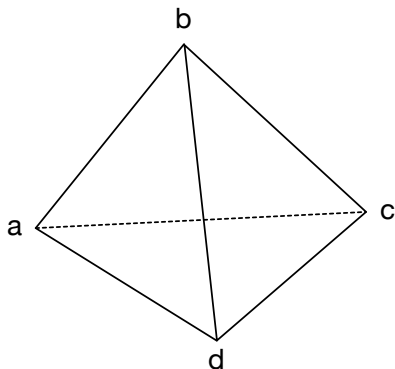
$$\Rightarrow \begin{array}{c} 12 \quad 23 \quad 31(+23) \\ \begin{array}{c} 1 \\ 2(+1) \\ 3(+2) \end{array} \begin{bmatrix} \boxed{1} & 0 & 1 \\ \cancel{1} & \boxed{1} & \cancel{1} \\ 0 & \cancel{1} & \cancel{1} \end{bmatrix} \end{array}$$

$$\mathcal{N}_1 = \begin{array}{c} 12 \quad 23 \quad 31 \\ \begin{array}{c} 1 \\ 2 \\ 3 \end{array} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \end{array}$$

- $\partial_0 = N_0$ is a 1×3 matrix with all 0 entries.
- $\text{rank } C_0 = \text{rank } Z_0 = 3$; $\text{rank } Z_1 = 1$, $\text{rank } B_0 = 2$
- $\beta_0 = \text{rank } Z_0 - \text{rank } B_0 = 3 - 2 = 1$
- $\beta_1 = \text{rank } Z_1 - \text{rank } B_1 = 1 - 0 = 1$

Take home exercise

The following simplicial complex contains 4 vertices, 6 edges, 3 triangles.
Compute its Betti numbers: $\beta_0 = 1$, $\beta_1 = 0$, $\beta_2 = 1$.



- Carlsson, G., Ishkhanov, T., De Silva, V., and Zomorodian, A. (2008). On the local behavior of spaces of natural images. *International journal of computer vision*, 76(1):1–12.
- Edelsbrunner, H. and Harer, J. (2010). *Computational Topology: An Introduction*. American Mathematical Society, Providence, RI, USA.